

Project:	Project 6 computes the shortest path to all vertexes of a graph from a distinguished vertex that serves as the origin. The input file specifies the graph. The output file records the shortest paths to all vertexes.																		
Program Files:	<table> <tr> <th>File</th><th>Description</th></tr> <tr> <td>p06.cpp</td><td>File p06.cpp contains functions that process command line arguments and exercise class <i>Graph</i>.</td></tr> <tr> <td>Graph06.h</td><td>File Graph06.h defines class Graph. class Graph defines member data and functions to manage a graph including finding the shortest path. A queue is used to find the shortest path and class Graph is derived from class Queue.</td></tr> <tr> <td>Graph06.cpp</td><td>File Graph06.cpp implements class Graph.</td></tr> <tr> <td>Queue06.h</td><td>File Queue06.h defines class Queue. class Queue defines member data and functions for a queue.</td></tr> <tr> <td>Queue06.cpp</td><td>File Queue06.cpp implements class Queue.</td></tr> <tr> <td>*06.h</td><td>All files containing class definitions must have the suffix 06.h.</td></tr> <tr> <td>*06.cpp</td><td>All files containing member function implementations must have the suffix 06.cpp.</td></tr> <tr> <td>p06make</td><td>File p06make contains instructions for program p06. Instructions are written for the UNIX utility <i>make</i>. Program p06 is contained in file p06.</td></tr> </table>	File	Description	p06.cpp	File p06.cpp contains functions that process command line arguments and exercise class <i>Graph</i> .	Graph06.h	File Graph06.h defines class Graph . class Graph defines member data and functions to manage a graph including finding the shortest path. A queue is used to find the shortest path and class Graph is derived from class Queue .	Graph06.cpp	File Graph06.cpp implements class Graph .	Queue06.h	File Queue06.h defines class Queue . class Queue defines member data and functions for a queue.	Queue06.cpp	File Queue06.cpp implements class Queue .	*06.h	All files containing class definitions must have the suffix 06.h .	*06.cpp	All files containing member function implementations must have the suffix 06.cpp .	p06make	File p06make contains instructions for program p06 . Instructions are written for the UNIX utility <i>make</i> . Program p06 is contained in file p06 .
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Command Line:	<p>Project 7 can be invoked with zero, one, or two program parameters. The first program parameter is the input file name. The second parameter is the output file name. Sample command lines together with corresponding actions by program p06 are shown below. Boldfaced type indicates data entered at the keyboard by the user.</p> <pre>\$ p06 Enter the input file name: i06.dat Enter the output file name: o06.dat \$ p06 i06.dat Enter the output file name: o06.dat \$ p06 i06.dat o06.dat</pre>																		
Input File:	<p>File i06.dat contains the number of vertexes, the distinguished vertex, <i>s</i>, from which the shortest path to every other vertex is computed, and a list of edges. (see Figure 1.). A representative Graph is contained in file ~tt/cs3613/i06.dat which you may copy to your home directory to test your project.</p> <p>File i06.dat contains integers as shown in Figure 1. The first integer is the number of vertexes. The next integer is the distinguished vertex <i>s</i>. Remaining integers are in pairs. Each pair represents a directed edge. The first integer in the pair is the origin of the edge and the second integer is the destination of the edge. Vertexes are numbered starting with vertex 0.</p>																		
Output File:	<p>The output consists of three columns titled <i>vertex</i>, <i>distance</i>, and <i>path</i>. List the vertexes in ascending order in the column labeled <i>vertex</i>. Print the distance to the vertex listed in the first column from the distinguished vertex in the column titled <i>distance</i>. List the path from the distinguished vertex to the vertex in the first column in the column labeled <i>path</i>. The Table in Figure 2 could have been produced by program p06 given edges listed in Figure 1.</p>																		

7	
2	
0	1
0	3
1	4
2	0
2	5
3	2
3	5
3	6
3	1
4	6
6	5

Figure 1. Input file format

Vertex	Distance	Path				
0	1	2	0			
1	2	2	0	1		
2	0	2				
3	2	2	0	3		
4	3	2	0	1		4
5	1	2	5			
6	3	2	0	3		6

Figure 2. Output file format.